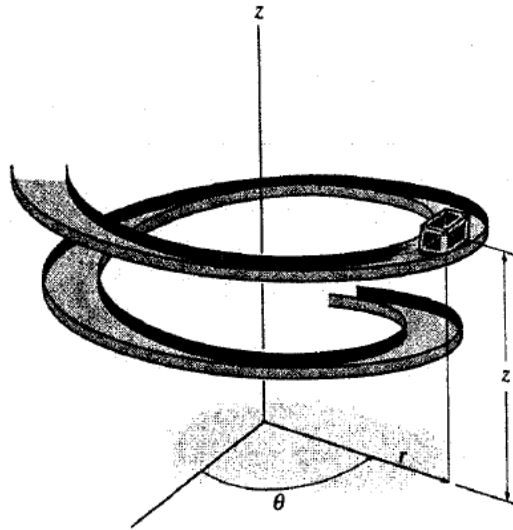


ÇALIŞMA SORULARI- POLAR HAREKET

12-171. The crate slides down the section of the spiral ramp such that $r = (0.5z)$ ft and $z = (100 - 0.1t^2)$ ft, where t is in seconds. If the rate of rotation about the z axis is $\dot{\theta} = 0.04\pi t$ rad/s, determine the magnitudes of the velocity and acceleration of the crate at the instant $z = 10$ ft.



$$r = 0.5z$$

$$z = 100 - 0.1t^2$$

Thus,

$$r = 50 - 0.05t^2$$

$$\dot{r} = -0.1t$$

$$\ddot{r} = -0.1$$

$$\dot{\theta} = 0.04\pi t \text{ rad/s} = 0.12566t \text{ rad/s}$$

$$\ddot{\theta} = 0.12566$$

$$\dot{z} = -0.2t$$

$$\ddot{z} = -0.2$$

At $z = 10$ ft,

$$10 = 100 - 0.1t^2$$

$$t = 30 \text{ s}$$

$$r = 50 - 0.05(30)^2 = 5$$

$$\dot{r} = -0.1(30) = -3$$

$$\ddot{r} = -0.1$$

$$\dot{\theta} = 0.12566(30) = 3.76991$$

$$\ddot{\theta} = 0.12566$$

$$z = -0.2(30) = -6$$

$$\dot{z} = -0.2$$

$$v_r = \dot{r} = -3$$

$$v_\theta = r\dot{\theta} = 5(3.76991) = 18.850$$

$$v_z = \dot{z} = -6$$

$$v = \sqrt{(-3)^2 + (18.850)^2 + (-6)^2} = 20.0 \text{ ft/s}$$

$$a_r = \ddot{r} - r\dot{\theta}^2 = -0.1 - 5(3.76991)^2 = -71.16$$

$$a_\theta = r\ddot{\theta} + 2\dot{r}\dot{\theta} = 5(0.12566) + 2(-3)(3.76991) = -21.99$$

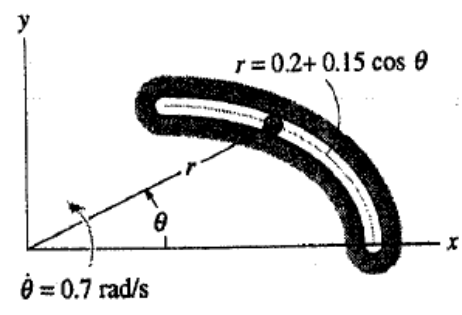
$$a_z = \ddot{z} = -0.2$$

$$a = \sqrt{(-71.16)^2 + (-21.99)^2 + (-0.2)^2} = 74.5 \text{ ft/s}^2 \quad \text{Ans}$$

***12-168.** The pin follows the path described by the equation $r = (0.2 + 0.15 \cos \theta)$ m. At the instant $\theta = 30^\circ$, $\dot{\theta} = 0.7$ rad/s and $\ddot{\theta} = 0.5$ rad/s². Determine the magnitudes of the pin's velocity and acceleration at this instant. Neglect the size of the pin.

$$r = 0.2 + 0.15 \cos \theta = 0.2 + 0.15 \cos 30^\circ = 0.3299 \text{ m}$$

$$\dot{r} = -0.15 \sin \theta \dot{\theta} = -0.15 \sin 30^\circ (0.7) = -0.0525 \text{ m/s}$$



$$\ddot{r} = -0.15[\cos\theta\ddot{\theta} + \sin\theta\dot{\theta}^2] = -0.15[\cos 30^\circ(0.7)^2 + \sin 30^\circ(0.5)^2] = -0.10115 \text{ m/s}^2$$

$$v_r = \dot{r} = -0.0525 \text{ m/s}$$

$$v_\theta = r\dot{\theta} = 0.3299(0.7) = 0.2309 \text{ m/s}$$

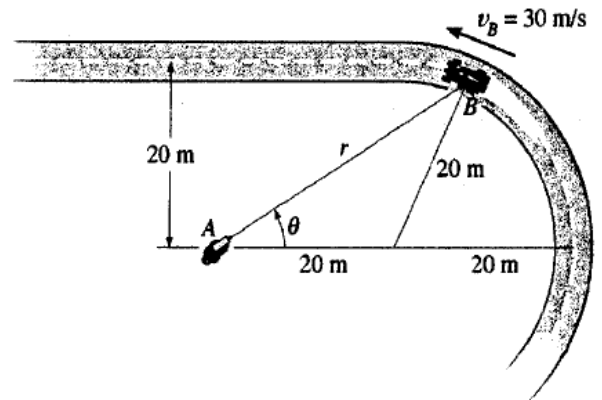
$$v = \sqrt{v_r^2 + v_\theta^2} = \sqrt{(-0.0525)^2 + (0.2309)^2} = 0.237 \text{ m/s} \quad \text{Ans}$$

$$a_r = \ddot{r} - r\dot{\theta}^2 = -0.10115 - 0.3299(0.7)^2 = -0.2628 \text{ m/s}^2$$

$$a_\theta = r\ddot{\theta} + 2\dot{r}\dot{\theta} = 0.3299(0.5) + 2(-0.0525)(0.7) = 0.09145 \text{ m/s}^2$$

$$a = \sqrt{a_r^2 + a_\theta^2} = \sqrt{(-0.2628)^2 + (0.09145)^2} = 0.278 \text{ m/s}^2 \quad \text{Ans}$$

12-167. A cameraman standing at *A* is following the movement of a race car, *B*, which is traveling around a curved track at a constant speed of 30 m/s. Determine the angular rate $\dot{\theta}$ at which the man must turn in order to keep the camera directed on the car at the instant $\theta = 30^\circ$.



$$r = 2(20\cos\theta) = 40\cos\theta$$

$$\dot{r} = -40\sin\theta\dot{\theta}$$

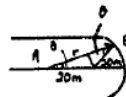
$$v = \dot{r}u_r + r\dot{\theta}u_\theta$$

$$v = \sqrt{(\dot{r})^2 + (r\dot{\theta})^2}$$

$$(30)^2 = (-40\sin\theta)^2(\dot{\theta})^2 + (40\cos\theta)^2(\dot{\theta})^2$$

$$(30)^2 = (40)^2[\sin^2\theta + \cos^2\theta](\dot{\theta})^2$$

$$\dot{\theta} = \frac{30}{40} = 0.75 \text{ rad/s} \quad \text{Ans}$$

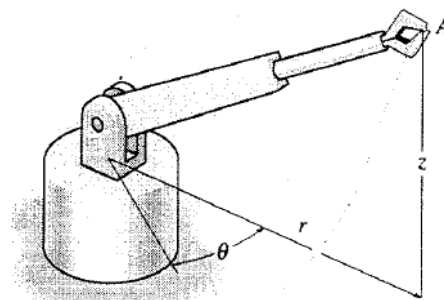


12-158. For a short time the arm of the robot is extending at a constant rate such that $\dot{r} = 1.5 \text{ ft/s}$ when $r = 3 \text{ ft}$, $z = (4t^2) \text{ ft}$, and $\theta = 0.5t \text{ rad}$, where t is in seconds. Determine the magnitudes of the velocity and acceleration of the grip *A* when $t = 3 \text{ s}$.

$$\theta = 0.5t \text{ rad} \quad r = 3 \text{ ft} \quad z = 4t^2 \text{ ft}$$

$$\dot{\theta} = 0.5 \text{ rad/s} \quad \dot{r} = 1.5 \text{ ft/s} \quad \dot{z} = 8t \text{ ft/s}$$

$$\ddot{\theta} = 0 \quad \ddot{r} = 0 \quad \ddot{z} = 8 \text{ ft/s}^2$$



At $t = 3$ s.

$$v_{\theta} = 3(0.5) = 1.5$$

$$\theta = 1.5 \quad r = 3 \quad z = 36$$

$$v_z = 24$$

$$\dot{\theta} = 0.5 \quad \dot{r} = 1.5 \quad \dot{z} = 24$$

$$v = \sqrt{(1.5)^2 + (1.5)^2 + (24)^2} = 24.1 \text{ ft/s} \quad \text{Ans}$$

$$\ddot{\theta} = 0 \quad \ddot{r} = 0 \quad \ddot{z} = 8$$

$$a_r = 0 - 3(0.5)^2 = -0.75$$

$$v_r = 1.5$$

$$a_{\theta} = 0 + 2(1.5)(0.5) = 1.5$$

$$a_z = 8$$

$$a = \sqrt{(-0.75)^2 + (1.5)^2 + (8)^2} = 8.17 \text{ ft/s}^2 \quad \text{Ans}$$